UHDAS and CODAS: Raising the Profile of Ocean Currents

Dr. Julia Hummon, University of Hawaii INMARTECH meeting, Bergen Norway, Oct. 2016

ADCP: Part 1

Acoustic Doppler Current Profiler

CODAS:

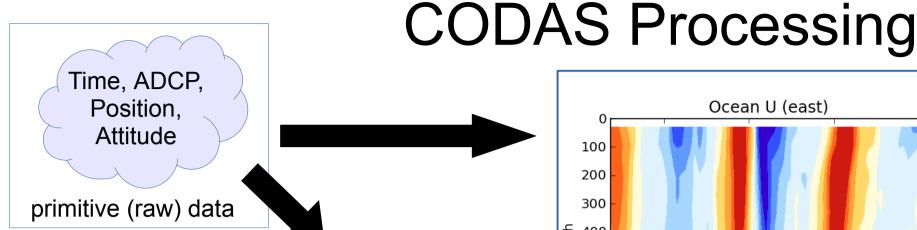
(refers to ADCP processing software)

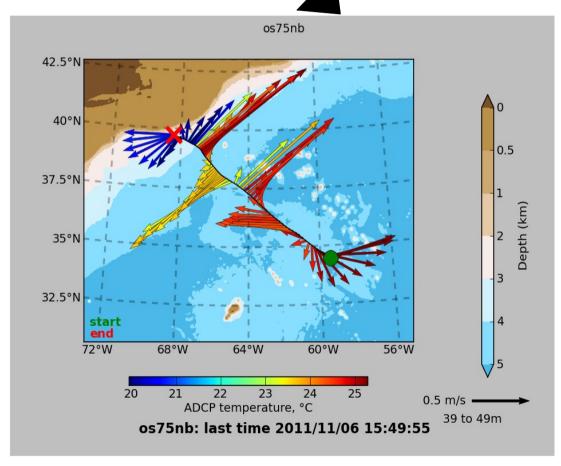
UHDAS: Part 2

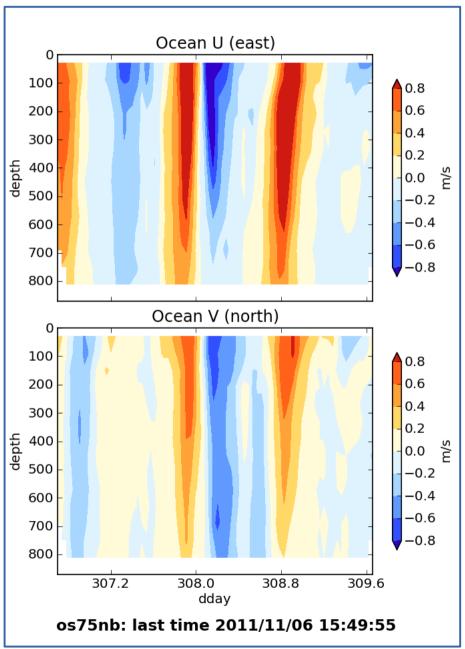
University of Hawaii Data Acquisition System

ADCP introduction

- Acoustic Doppler Current Profiler (shipboard)
- 4-beams, Doppler shifted currents as ship moves
- To obtain ocean currents:
 - (1) transform beam coordinates into instrument coordinates
 - (2) rotate horizontal velocities into ship coordinates using transducer angle in the hull (EA command for VmDAS)
 - (3) rotate velocities on ship to North (using <u>heading</u>)
 - yields measured velocities in Earth coordinates
 - (4) remove ship's speed using positions
- link to diagrams







CODAS processing

CODAS = Common Ocean Data Access System

GOALS:

- science-ready data when finished
- accessible to anyone/many
- balance: Big Automatic Script



Fine-tune the machinery if problems exist

CODAS processing: 2 modes

(1) load averaged data into CODAS database

- 1980's PINGDATA
- VmDAS: *.LTA, *.STA

(no single-ping editing)

(2) process single-ping data

- beam-to-earth coordinates
- single-ping editing (acoustic interference, bottom)
- create averages; save to disk
- load averages into CODAS database



Next: "post-processing steps"

CODAS post-processing:

- View figures and logfiles
- Fix heading:
 - patch gappy but accurate heading correction (if relevant)
 - apply time-dependent heading correction
- Determine corrections/calibrations, then apply
 - remaining transducer offset
 - scale factor (if relevant)
 - transducer-GPS offset (in meters)
- Manually edit out bad data ("gee-autoedit" tutorial)
 - graphically select bins, profiles
 - using thresholds
- check calibrations
- make figures (web page); export data (matlab, netCDF)

CODAS software tools:

Tools for (averaged) data in CODAS to:

- view CODAS database (currents, backscatter)
- use plotting programs to help
 - assess quality of heading and position devices
 - plot cruise tracks, make web page with plots
- export netCDF file (averaged data: all bins, profiles)

CODAS software tools:

- Tools for or raw (single-ping) ADCP data:
- visualization of beam values
 - RSSI (signal return)
 - beam velocity
- estimate EA (transducer angle)
- conversion of NMEA strings to "rbin" data files
 - N1R, N2R, N3R (from VmDAS)
 - UHDAS raw serial data
- tools to plot rbin data:
 - plot POSMV quality
 - plot navigation over topography
 - plot one (or compare two) rbin data streams

UHDAS and CODAS: Raising the Profile of Ocean Currents

Outline:

ADCP:

Acoustic Doppler Current Profiler

CODAS:

(refers to ADCP processing software)

UHDAS:

Part 2

University of Hawaii Data Acquisition System

UHDAS: What are our goals?

- Enhance the utility and visibility of ADCP data
- Provide viable ocean currents at sea:
 - Data should be useful for science and operations
 - Data should be as close to "final" as possible (for an automated system)
 - Require minimal post-processing for science
- Reprocessing on multiple operating systems (Linux, Mac, Windows) – see CODAS

people UHDAS: What are our ₄goals?

- Happy Scientists (good data)
- Happy Techs (operationally useful, easy)
- Happy Managers
 - data managers (predictable)
 - ship operations (monitored, useful displays)
 - funding (happy scientists, techs, ship ops)

Summary: Everyone is happy
Everyone is excited about ADCP data

What does UHDAS do?

Performs these tasks:

- Data acquisition (TRDI ADCPs)
- Data processing (create ocean currents--cods)
- Generates data products for science
- Creates tools and components for monitoring
 - monitoring (plots) at sea
 - monitoring (daily email) on shore

UHDAS Components: Acquisition

- runs on linux (Xubuntu 14.04 at present)
- acquisition:
 - communication with ADCPs
 - serial acquisition with timestamps
- reliable, robust, duplicate feeds
 - multiple GPS feeds
 - one computer, multiple ADCPs
 - reliable heading, and accurate heading
- simple graphical interface for settings/stop/start
 - Green=Good, Red=Rubbish

UHDAS Components: Processing, Plots, and Data

- incremental single-ping processing:
 - stage averages; display 5-minute profile on web site
- load averages, create vector and contour plots
- other plots (on shipboard web site)
 - bridge plot (knots and direction at "surface)
 - profile of vectors (at various depths)
 - heading correction plot (use accurate heading QC)
 - beam velocities
- data (on shipboard web site)
 - matlab (various), netCDF (and CODAS database)

UHDAS Monitoring

At Sea (shipboard website):

- plots for science and bridge
- averaged data for science
- raw data (for uber-user to reprocess at sea)
- example web site

On Land (daily email):

- daily email with ascii status message
- 100K tarball with data snippet, diagnostic info
- table of email status

Benefits of UHDAS

Real-time accessible data for

- Science at sea, eg:
 - larval recruitment and dispersion
 - context for other measurements
 - drifters
- Operations
 - ROV deployment
 - CTD wire angle
 - mooring deployment

Benefits of UHDAS

- Reliable, simple interface for Techs
- Remote monitoring by ADCP guru (via daily email)
- Long-term usefulness:
 - Open source software
 - Existing path to NODC (via R2R, for USA/NSF data)
- Open communication with scientists and techs

UHDAS Installation Note

UHDAS is not a program, but a complex set of code and system configurations.

Setting up a new UHDAS installation requires Linux system administration skills, an understanding of UHDAS, and detailed knowledge of the particular suite of instruments and network environment on the ship.

UHDAS+CODAS documentation

- what is documented
 - CODAS processing (with tutorials); long history
 - installation of CODAS software
 - UHDAS: at sea (web site, data, plots)
 - UHDAS: for techs how to run it
- presentations only (but not documentation):
 - how UHDAS works
- not documented
 - UHDAS installation (Xubuntu, *.deb, *.tar.gz, CODAS)
 - UHDAS configuration (serial, ntp, mail, processing)